# Package 'dfdr' 

February 23, 2023
Type Package
Title Automatic Differentiation of Simple Functions
Version 0.2.0
Description Implementation of automatically computing derivatives
of functions (see Mailund Thomas (2017) <doi:10.1007/978-1-4842-2881-
$4>$ ). Moreover, calculating gradients, Hessian and Jacobian matrices is possible.
License GPL-3
Encoding UTF-8
Imports methods, purrr, rlang, R6, pryr
Suggests tinytest
NeedsCompilation no
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Repository CRAN
Date/Publication 2023-02-23 10:30:02 UTC
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## Description

Differentiate a function for a single variable.

## Usage

$$
\mathrm{d}(\mathrm{f}, \mathrm{x}, \text { derivs }=\mathrm{NULL})
$$

## Arguments

f
x
derivs

The function to differentiate.
The variable that f should be differentiated with respect to.
An S4 class of type fcts that defines additional derivatives. See fcts for details.

## Details

The following functions are already supported:
sin, sinh, asin, cos, cosh, acos, tan, tanh, atan, exp, log, sqrt, c, vector, numeric, rep and matrix. Notably, for the functions: c , vector, numeric, rep and matrix the function is ignored during differentiation.

## Value

For example function f and symbol x :
$d f / d x$

## Examples

```
library(dfdr)
d(sin, x)
f <- function(x) - sin(x)
d(f, x)
# Initialize list
lst <- dfdr::fcts()
# The function which should be added
f <- function(x) x^2
# The dervative function of f
f_deriv <- function(x) 2*x
# add new entry to list
lst <- fcts_add_fct(lst, f, f_deriv)
g <- function(z) f(z)
d(g, z, lst)
```

fcts $S 4$ class fcts

## Description

A S4 class containing additional functions which can be used for calculating derivatives with $d()$. To create a class the function $f c t s()$ should be used.
Adding functions is only possible via the function add_fct.

## Details

The following functions are already supported:
$\sin , \sinh$, asin, cos, cosh, acos, tan, tanh, atan, exp, log, sqrt, c, vector, numeric, rep and matrix.
Notably, for the functions: c, vector, numeric, rep and matrix the function is ignored during differentiation.

## Slots

funs A list containing the specified functions. This slot should not be accessed and is used only internally.

## See Also

d()

## Examples

```
library(dfdr)
# Initialize list
lst <- dfdr::fcts()
# The function which should be added
f <- function(x) x^2
# The dervative function of f
f_deriv <- function(x) 2*x
# add new entry to list
lst <- fcts_add_fct(lst, f, f_deriv)
g <- function(z) f(z)
df <- d(g, z, lst)
df
```

```
fcts_add_fct appending a S4 class of type fcts
```


## Description

A function which appends a $S 4$ class of type $f c t s$ with a new function-derivative pair.

## Usage

fcts_add_fct(lst, f, f_deriv, keep = FALSE)

## Arguments

lst is the S 4 class of type fcts. Newly created by fcts()
$\mathrm{f} \quad$ is the function which should be differentiated. The argument has to be of type function.
f_deriv is a function defining the derivative of $f$. The argument has to be of type function.
keep is a logical value. If set to TRUE the function $f$ is ignored of d() . The default value is FALSE.

## Details

The following functions are already supported:
sin, sinh, asin, cos, cosh, acos, tan, tanh, atan, exp, log, sqrt, c, vector, numeric, rep and matrix.
Notably, for the functions: c , vector, numeric, rep and matrix the function is ignored during differentiation.

## Value

a S 4 class of type $f c t s$ extended by the new function-derivative pair.

## Note

The body of $f$ and $f_{-}$deriv have to be defined without curly brackets.

## Examples

```
library(dfdr)
# Initialize list
lst <- dfdr::fcts()
# The function which should be added
f <- function(x) x^2
# The dervative function of f
f_deriv <- function(x) 2*x
# add new entry to list
lst <- fcts_add_fct(lst, f, f_deriv)
```

```
g <- function(z) f(z)
df <- d(g, z, lst)
df
```

gradient Compute the gradient-function of a function.

## Description

Creates a function that computes the derivative of a function with respect to each parameter and return a vector of these.

## Usage

gradient(f, use_names, ...)

## Arguments

f
A function
use_names
Should the gradient add variable names to the output of the function?
The variable names for which gradients should be calculated

## Value

A function that computes the gradient of f at any point.

## Examples

```
f <- function(x, y) x^2 + y^2
df <- gradient(f, FALSE, x, y)
df(1, 1)
```

    hessian Compute the Hessian-function of a function.
    
## Description

Creates a function that computes the second-order derivatives of a function with respect to each pair of parameters and return a vector of these.

## Usage

hessian(f, use_names = FALSE, ...)

## Arguments

| f | A function |
| :--- | :--- |
| use_names | Should the gradient add variable names to the output of the function? |
| $\ldots$. | The variable names for which gradients should be calculated |

## Value

A function that computes the gradient of $f$ at any point.

## Examples

$\mathrm{f}<-\mathrm{function}(\mathrm{x}, \mathrm{y}) \mathrm{x} * * 2+\mathrm{y} * * 2$
h <- hessian(f, FALSE, $x, y)$ h(0, 0)

```
jacobian jacobian function
```


## Description

Creates a function that computes the jacobi-matrix of a function for one specific variable. Hereinafter the variable is called $y$. The derivative is calculated with respect to one of the arguments of the function. Subsequently, the variable is called $x$. The returned function can be called at any possible point of $x$.

## Usage

jacobian(f, y, x, derivs = NULL, num_functions = NULL)

## Arguments

f
x
derivs
num_functions
y The variables to compute the derivatives of (the dependent variable). For example: $d f / d x$
A function The variables to which respect the variables are calcualted (the independent variable). For example: $d f / d x$ optional input defining own functions which should be used. See d() for details. optional input defining number of functions otherwise a squared matrix form is assumed.

## Details

The function jacobian is intended for using it for functions accepting vectors (in case of $x$ ) and returns a vector (for $y$ ).
Mentionable, only integers are allowed for indexing the vectors. Moreover, only one element at the time can be changed. For instance, $y[1]$ is permitted. In contrast, $y[1.5]$ or $y[v a r i a b l e]$ will throw an error.
As usually it is possible to define new variables. If $x$ and/or $y$ are found at the right side of the assignment operator the variable is replaced in all following lines. See the example below:

```
# Old code
a <- x[1]
b <- 3
y[1] <- a*b
# New code
b <- 3
y[1] <- a*3
```

Furthermore, it is possible to use if, else if, else blocks within the function. However, the dependent variable have to be located at the left side of the assignment operator. This restriction is necessary as variables found in previous lines are replaced in the following lines.

```
# allowed code
```

f <- function(x, t) \{
y <- numeric(2)
$y[1]<-2 * x[1]^{\wedge} 3$
if $(t<3)$ \{
$y[2]<-x[2]^{\wedge} 2$
\} else \{
$y[2]<-x[2]^{\wedge} 4$
\}
return(y)
\}
\# not allowed code
$\mathrm{f}<-$ function( $\mathrm{x}, \mathrm{t}$ ) \{
$y<-$ numeric(2)
$y[1]<-2 * x[1] \wedge 3$
a <- 0
if $(t<3)$ \{
a <- x[2]^2
\} else \{
a <- x[2]^4
\}
$y[2]<-a$
return(y)
\}

## Value

A function that computes the jacobi-matrix of $f$. Notably, it expects the dame arguments as the input function $f$.

## Examples

```
f <- function(x) {
    y <- numeric(2)
    y[1] <- x[1]^2 + sin(4)
    y[2] <- x[2]*7
    return(y)
}
jac <- dfdr::jacobian(f, y, x)
jac(c(1, 2))
```

simplify Simplify an expression by computing the values for constant expres-
sions

## Description

Simplify an expression by computing the values for constant expressions

## Usage

simplify (expr)

## Arguments

expr An expression

## Value

a simplified expression

## Examples

$e x<-q u o t e\left(a * 0+b^{\wedge} 2+0\right)$
simplify(ex)

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